

Cutting Resilient Networks

Xing Shi Cai

Cecilia Holmgren



Fiona Skerman



Uppsala University (Sweden)

Luc Devroye



McGill University

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k -cut on Paths and Some Trees

Xing Shi Cai

Cecilia Holmgren



Fiona Skerman



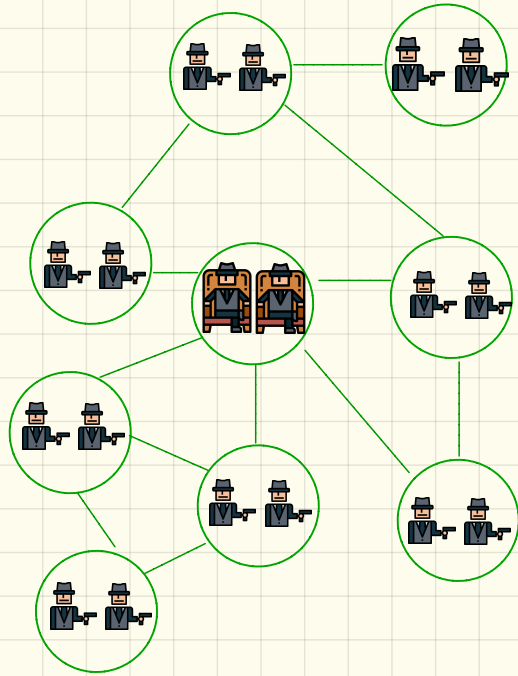
Uppsala University (Sweden)

Luc Devroye



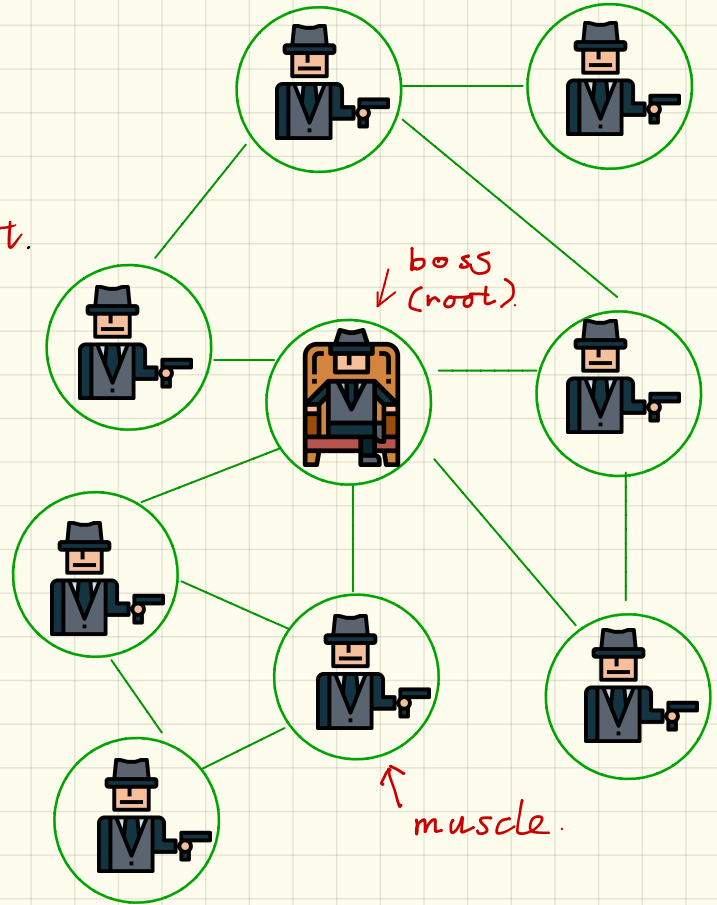
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The Model



Rooted Graph

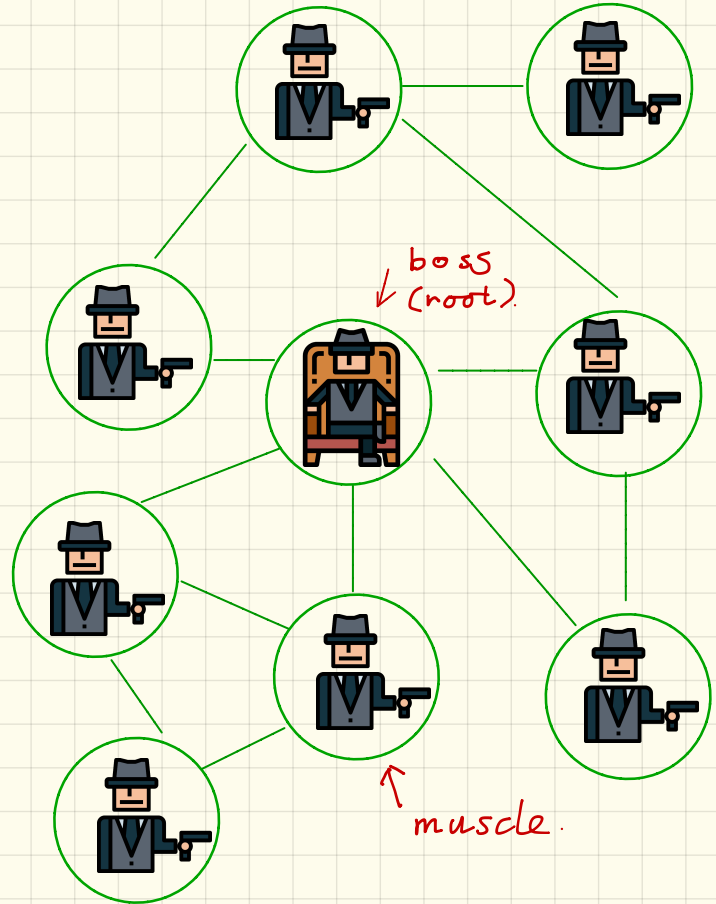
- A **rooted graph** has one node labelled as the **root**.
- Can be viewed as models for criminal networks, terrorist cells, or **botnets** (malicious P2P networks).



Destroying a Network

We do not know where is the **boss**. So we

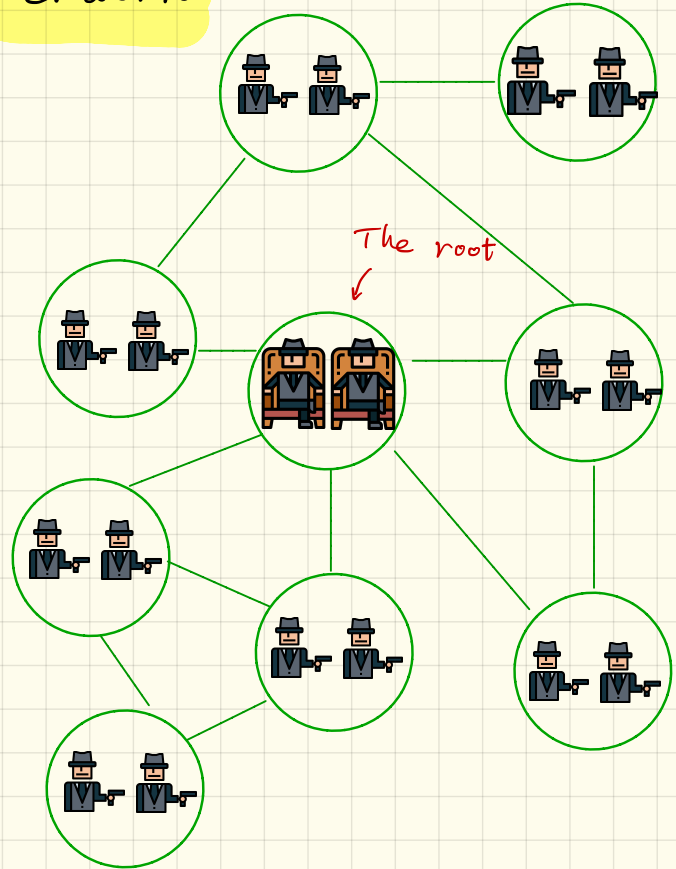
1. Choose a node unif. at random. Remove it.
2. If the graph becomes **disconnected**, keep only the component containing the **boss**.
3. Repeat until **the root** is removed.



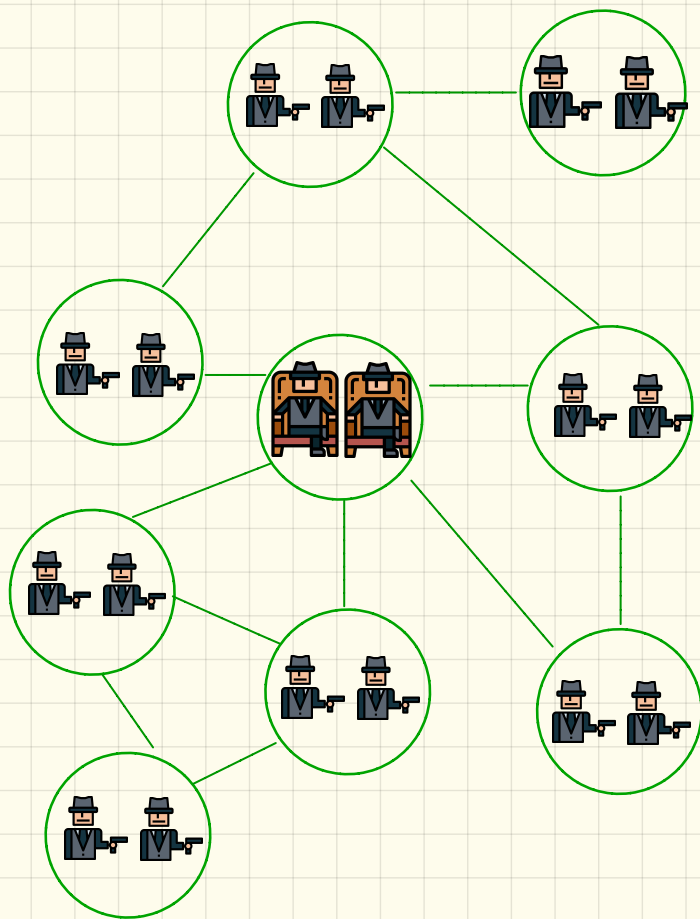
Destroying a Resilient Network

Assume each node has $k \in \mathbb{N}$ backups. We

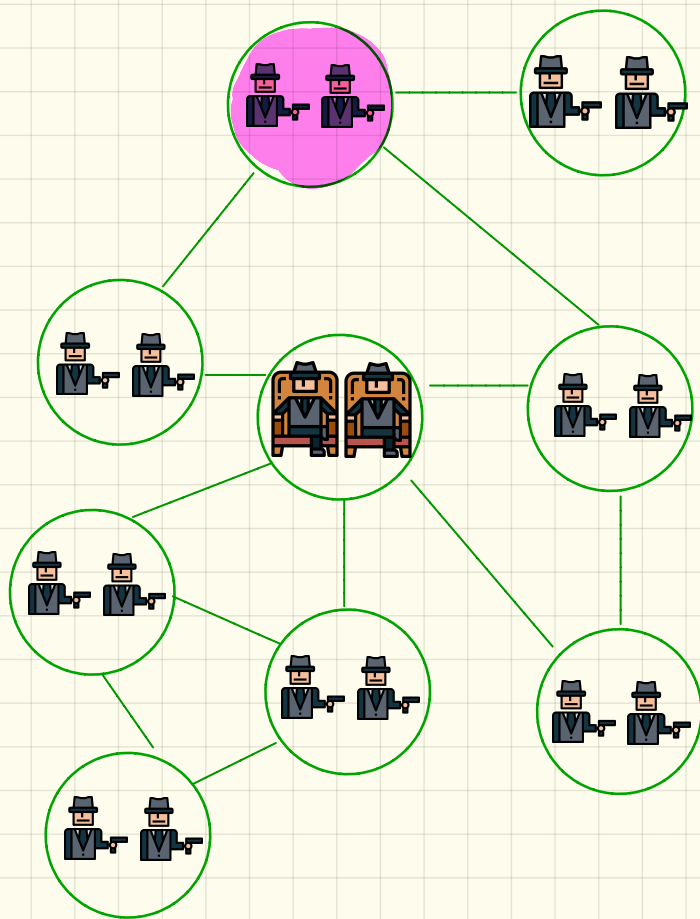
1. Choose a node unif. at random. Remove one of its back up (cut it once)
2. Remove a node if all k backups are gone.
3. Keep only the component containing the root.
4. Repeat until the root is gone.



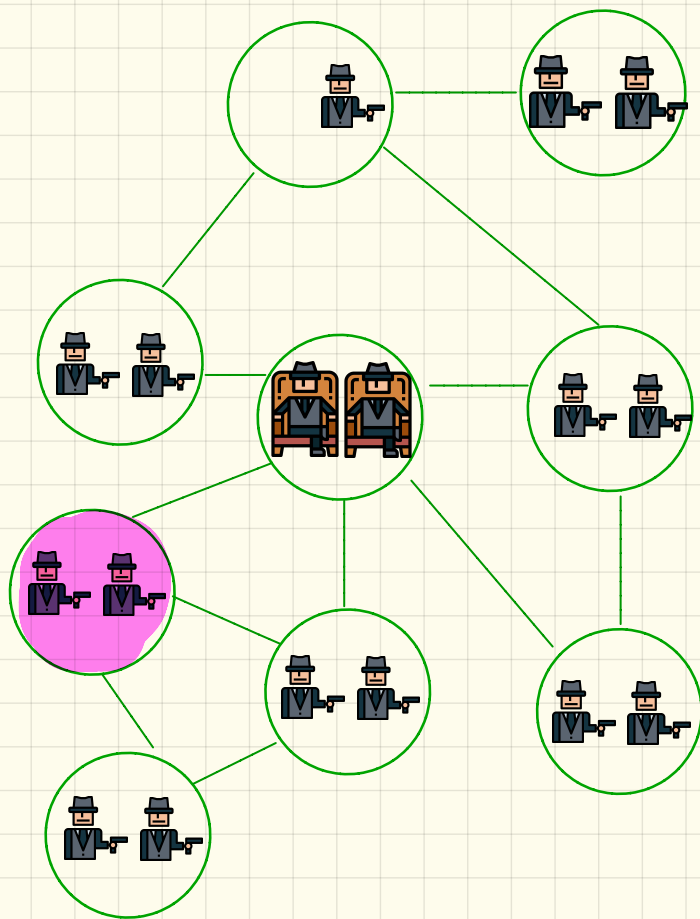
Example



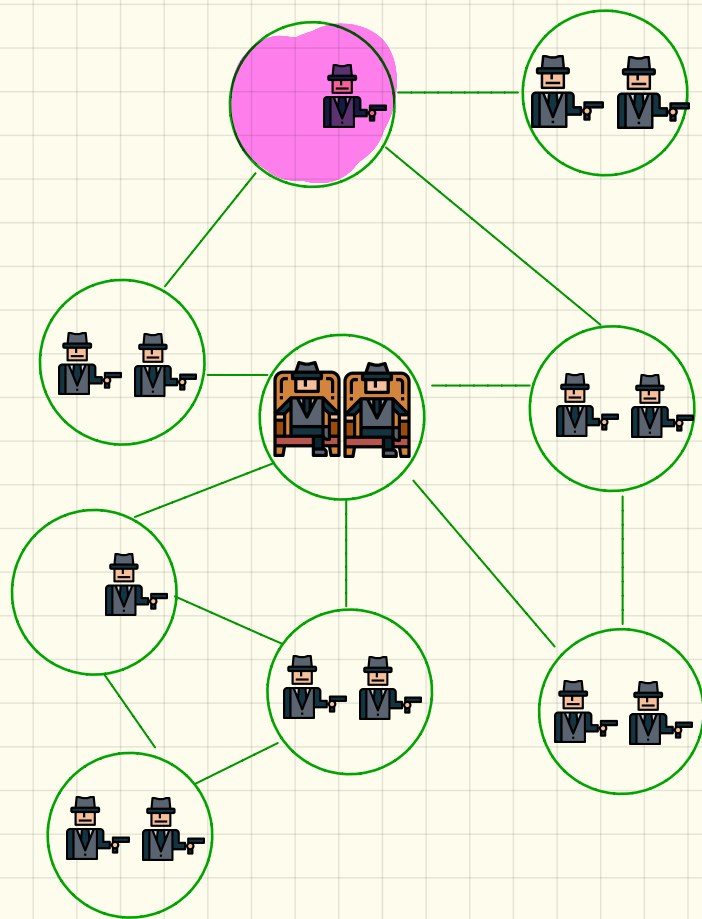
Example



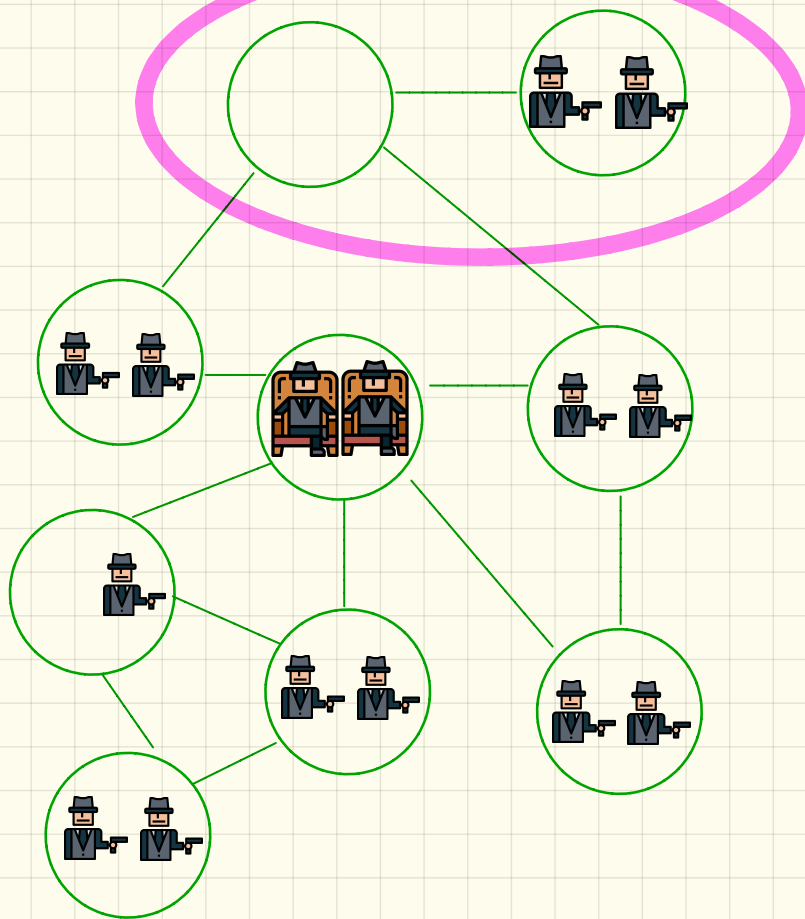
Example



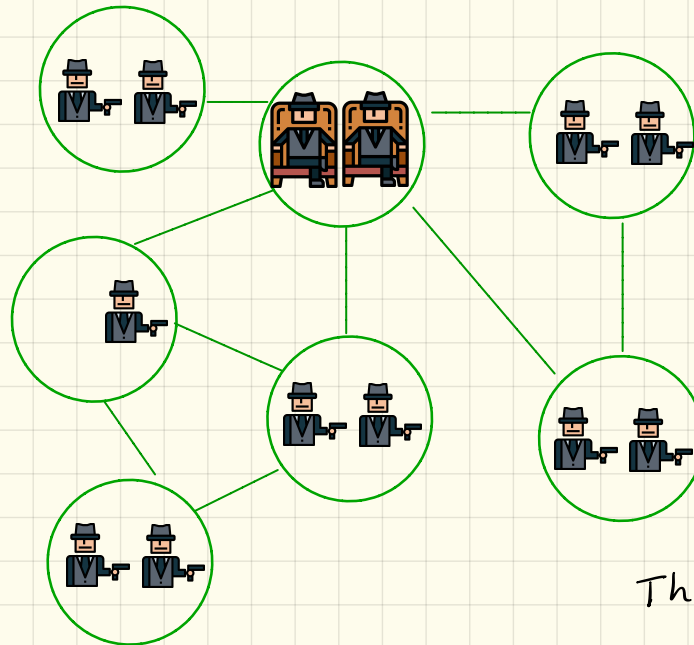
Example



Example

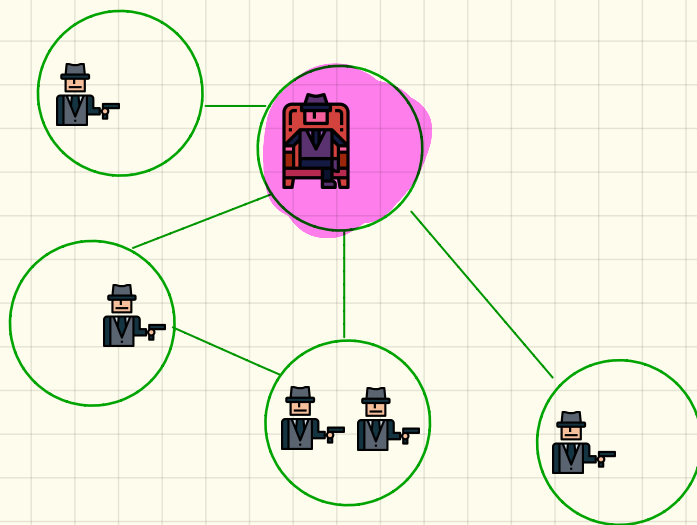


Example



This continues ...

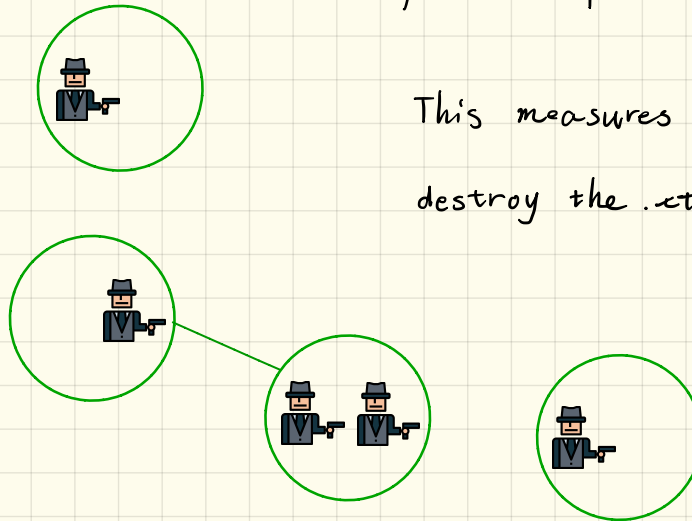
Example



until the **root** is gone.

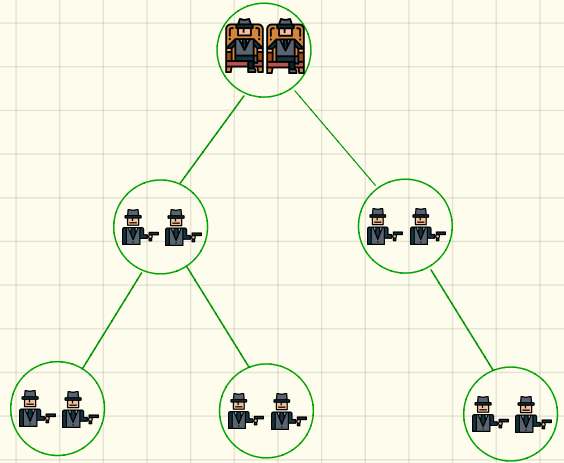
Example

We most ly care $X(G_n)$ —
the number of cuts needed to
for the process to end.

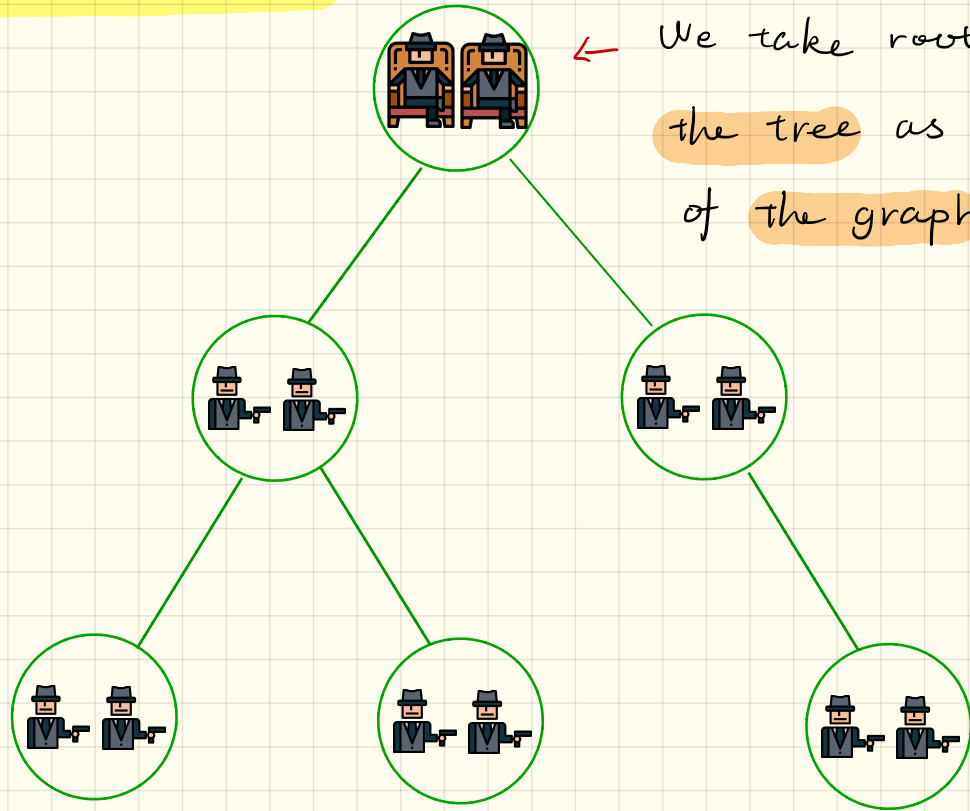


This measures how hard it is to
destroy the network.

Cutting Rooted Trees



Cutting Rooted Trees



← We take root of
the tree as root
of the graph.

The case $k=1$

- Let \mathbb{T}_n be a rooted tree with n vertices.
- Let $K(\mathbb{T}_n)$ be the num. of cuts needed to destroy \mathbb{T}_n .
- $K(\mathbb{T}_n)$ has been studied for $k=1$ in
 - Cayley trees Meir and Moon (1970)
 - Complete Binary trees Janson (2004).
 - Conditional Galton-Watson trees Janson (2006).
 - Addario-Berry, Broutin, Holmgren (2014).
 - Binary Search Trees and Split Trees Holmgren (2011, 2012).
 - RRT Meir and Moon (1974) Prmota et al. (2009).

An equivalent model $k=1$

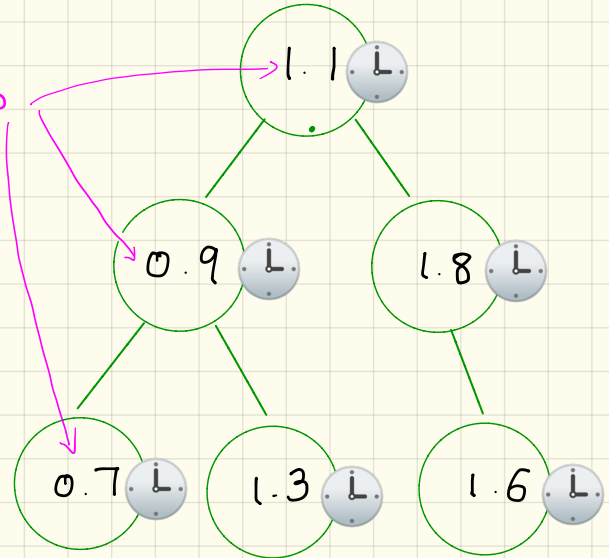
- We give each node v a time stamp

$$T_v \sim \text{Exp}(1) \text{ iid}$$

- We cut a node v at time

T_v if v is still in the tree.

- Each time we are still cutting a uniform random node.



Idea comes from Svante (2004).

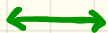


Records

v is in tree at time T_v



No ancestor of v died before T_v

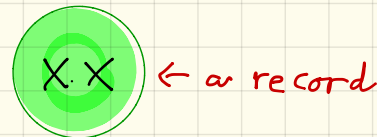
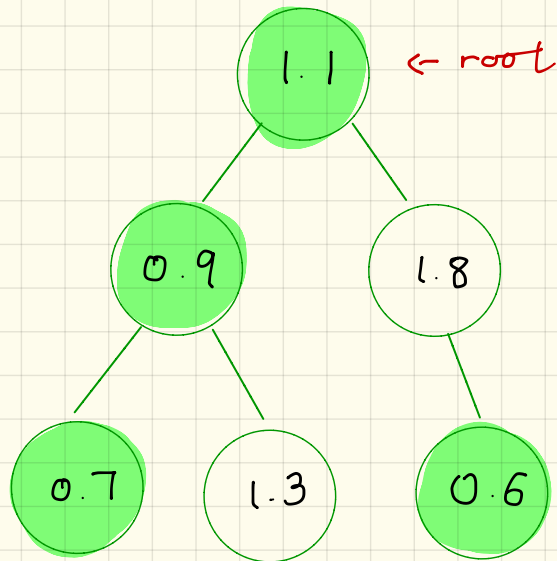


$$T_v < \min_{u: u \prec v} T_u.$$

Janson call T_v or (simply v)

a record.

of records = # of cuts



Generalize to $k \geq 1$.

- Each node v get timestamps

$T_{1v}, T_{2v}, \dots \sim \text{Exp}(1)$ iid.

- Let $G_{rv} = \sum_{i=1}^k T_{iv} \sim \text{Gam}(k, 1)$

- Cut v at time G_{rv} if v is still in

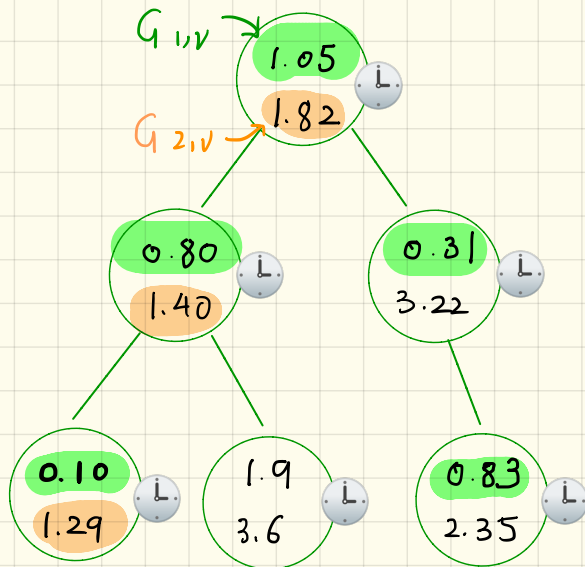
tree \longleftrightarrow

Time u dies.

$$G_{rv} < \min_{u: u \neq v} G_{ku}$$

- Call such G_{rv} or (simply v) an r -record.

cuts \rightarrow
$$K(\mathbb{I}_n) = \sum_{r=1}^k K_r(\mathbb{I}_n)$$
 \leftarrow Number of r -records.



$X \cdot X \leftarrow 1$ -record

$X \cdot X \leftarrow 2$ -record

K-cut on a path



The simplest graph - path

Let P_n be a path of n nodes.

For all graphs G_n of n nodes,

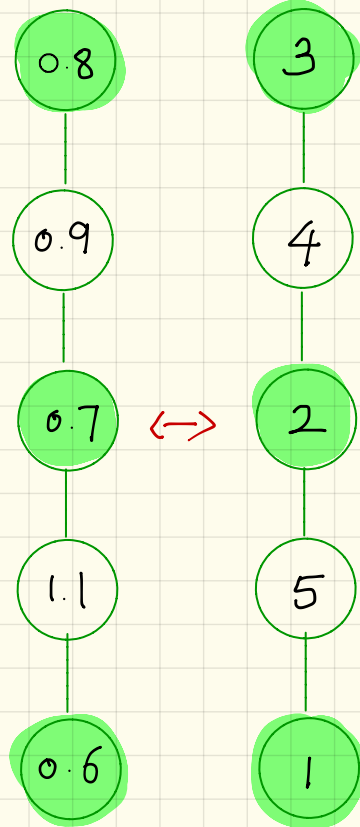
$$K(P_n) \preceq K(G_n)$$

i.e., a path is the easiest to cut.

Quiz: Which graph is the hardest to cut?

For $k=1$, $K(P_n) \sim \#$ of records
in unif. rand. permutation.

$$\frac{K(P_n) - \log(n)}{\sqrt{\log(n)}} \xrightarrow{d} N(0,1) \quad (\text{normal})$$

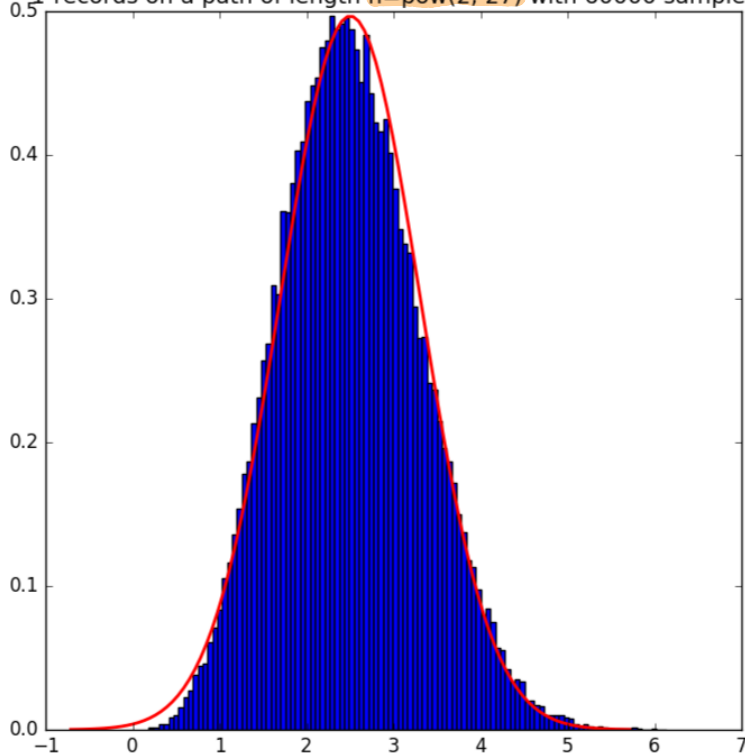


$$\begin{aligned} \mathbb{E}(K(P_n)) &= \frac{1}{1} + \frac{1}{2} + \dots + \frac{1}{n} \\ &= H_n \sim \log n \end{aligned}$$

Simulation for $k=2$.

$$2^{27} \approx 10^8$$

1-records on a path of length $n=\text{pow}(2, 27)$ with 60000 samples



Looks like a normal.

Tried to prove.

But failed!



More simulations. $k=2$

=====
Analysis 30000 samples for path length 536870912 (2^{29}) $\approx 10^9$
=====

Mean 58141.156467

Mean divided by \sqrt{n} 2.509278

Variance 358057278.161121

Variance divided by n 0.666934

The 3 moment divided by $\text{variance}^{(3/2)}$ is 0.238525

The 4 moment divided by $\text{variance}^{(4/2)}$ is 2.919119

The 5 moment divided by $\text{variance}^{(5/2)}$ is 2.326212

The 6 moment divided by $\text{variance}^{(6/2)}$ is 14.591784

• This *cannot* be a normal distribution.

• The expectation is order \sqrt{n}

• The variance is order n .

} Can we find the constant?



The moment - Expectation.

- Let $I_{r,i+1}$ be the indicator that $i+1$ is a r -record.

- Then

$$\mathbb{E}(I_{r,i+1}) = \int_0^\infty \underbrace{\frac{e^{-x} x^{r-1}}{r!}}_{\text{Density of } Gr,i+1} \underbrace{\mathbb{P}(\text{Gam}(k) > x)}_{\substack{\text{Every node above } i+1 \\ \text{dies after } x}} \approx \underbrace{\frac{(k!)^{\frac{1}{k}}}{k} \frac{\Gamma(\frac{r}{k})}{\Gamma(r-1)}}_{\text{constant}} i^{-\frac{r}{k}}$$

- Summing this up

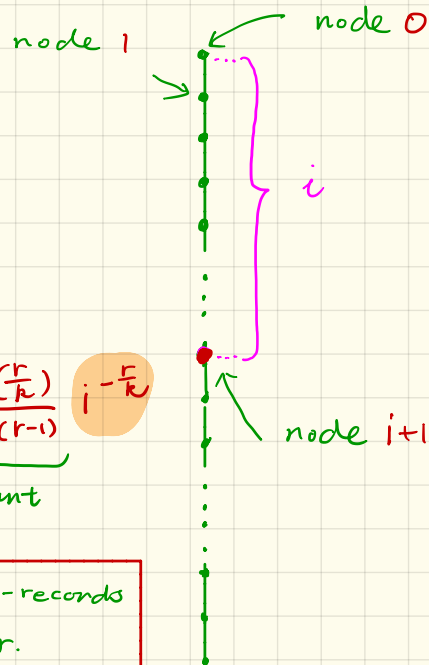
$$\mathbb{E}(K_r(P_n)) = \sum_{i=0}^n \mathbb{E}(I_{r,i}) \approx \eta_{k,r} \cdot n^{1-r/k}$$

Only 1-records matter.

- For $k=2$,

$$\mathbb{E}(K_1(P_n)) \sim \sqrt{2\pi n} \approx 2.5066 \sqrt{n}$$

2.5066 by simulation



The moment - Variance

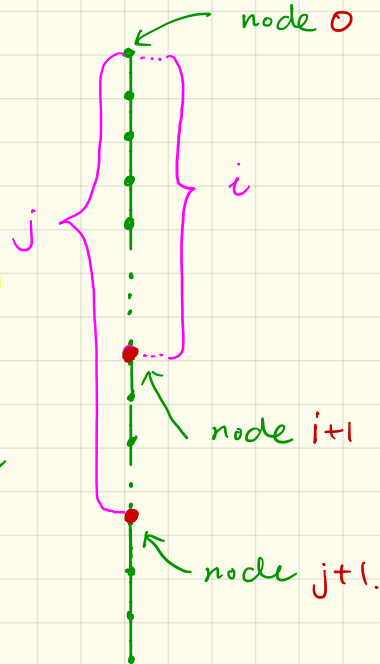
- We only care about 1-records.
- Similar to expectation

$$\frac{\mathbb{E}(K_1(P_n)^2)}{n^{2-\frac{2}{k}}} \sim \underbrace{\frac{\Gamma(\frac{2}{k})(k!)}{k-1} + \frac{\pi \cot(\frac{\pi}{k}) \Gamma(\frac{2}{k})(k!)^{\frac{2}{k}}}{2(k-2)(k-1)}}_{\text{Rather complicated constant}}$$

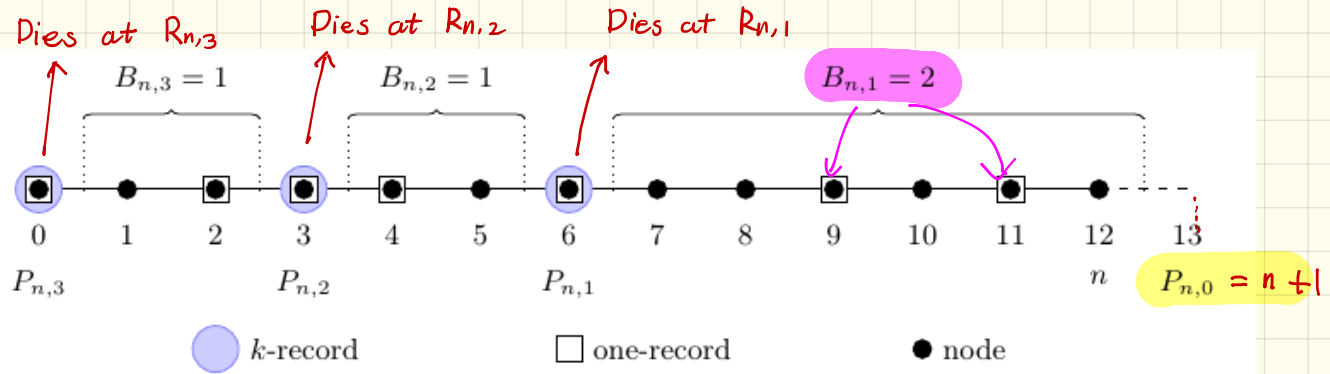
- When $k=2$

$$\text{Var}(K_1(P_n)) \sim \left(\frac{\pi^2}{2} + 2 - 2\pi\right) n \approx 0.651 n.$$

- Higher moments seem to be harder!



The limit distribution



- Let $P_{n,1}, P_{n,2}, \dots$ be the position of k -records. (where the path breaks).
- Let $R_{n,1}, R_{n,2}, \dots$ be the time they die
- Conditioning on $P_{n,1}, P_{n,2}, \dots, R_{n,1}, R_{n,2}, \dots$

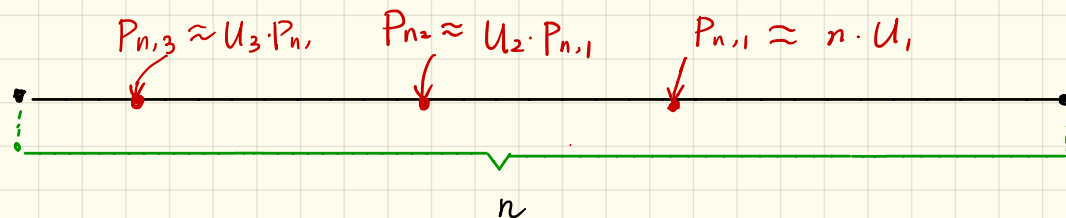
$$B_{n,j} \approx \text{Bin} \left(\underbrace{P_{n,j-1} - P_{n,j}}_{\substack{\# \text{ of nodes} \\ \text{between } P_{n,j-1}, P_{n,j}}}, \underbrace{\mathbb{P}(\text{Exp}(1) < R_{n,j})}_{\substack{\text{Prob of being a 1-record.} \\ \text{Time segment breaks off.}}} \right)$$

$B_{n,j}$ \uparrow one-records between $P_{n,j-1}, P_{n,j}$



The limit distribution

- Let U_1, U_2, U_3, \dots be iid $\text{Unif}[0, 1]$.



- Let E_1, E_2, E_3, \dots be iid $\text{Exp}(1)$. We can also approximate

$$R_{n,1} \approx n^{-\frac{1}{k}} (k! E_1)^{\frac{1}{k}}, \quad R_{n,2} \approx (P_{n,1})^{-\frac{1}{k}} (k! E_2 U_1 + k! E_2)^{\frac{1}{2}}, \dots$$

\nwarrow when $P_{n,1}$ dies \nwarrow when $P_{n,2}$ dies.

$$\frac{K(P_n)}{n^{1-\frac{1}{k}}} \xrightarrow{d} \sum_{P=1}^{\infty} B_P := B_n$$

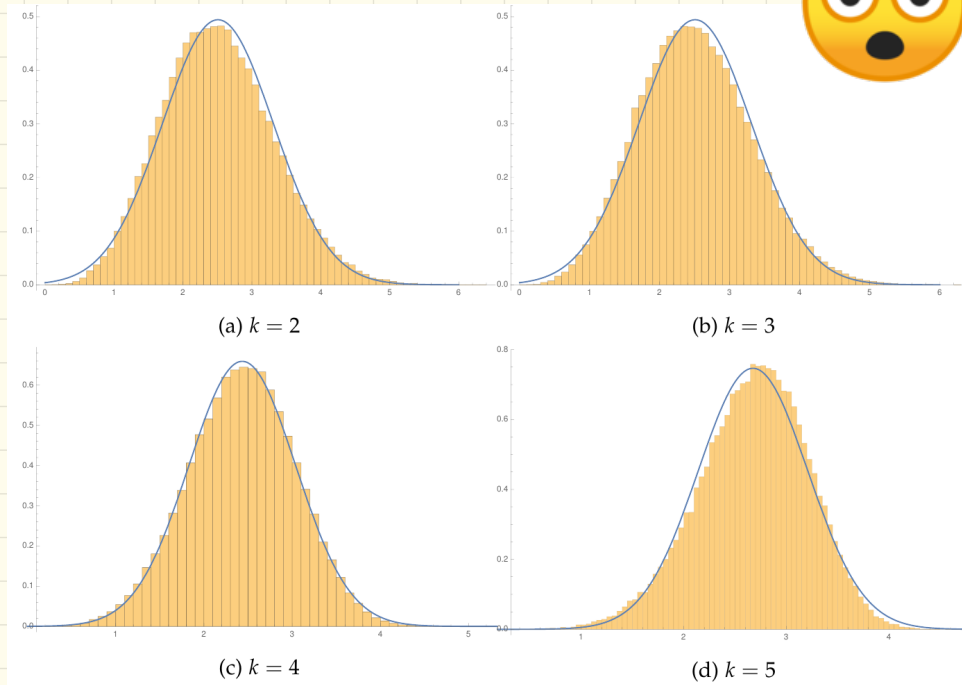
B_n rescaled

All moments
also converge.

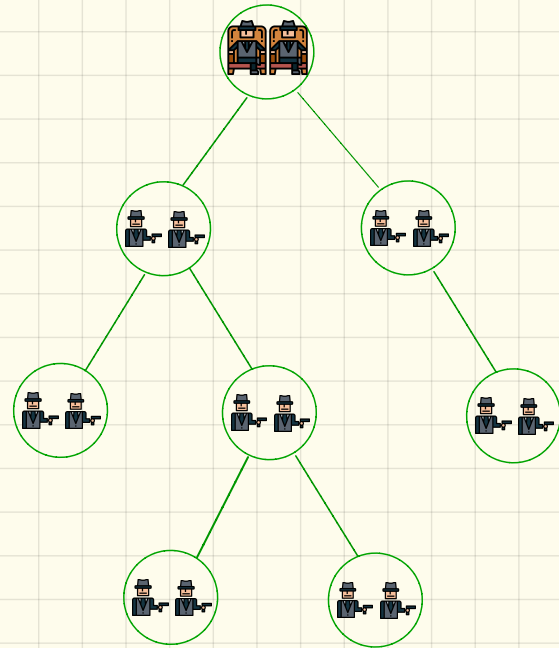
complicated function of $U_1, U_2, \dots, E_1, E_2, \dots$

The simulation

- We do not have the density function of B_k .
- But simulation suggests that it's close to a normal distribution.
- Not everything that looks normal is normal!




Complete Binary Trees,
Conditional Galton-Watson
Trees, and many more



The current landscape for $k \geq 2$.

● Cai, Devroye, Holmgren, Sherman 2019. EJP

● Cutting resilient networks — complete binary trees. Cai, Holmgren. 2018, arxiv

● The k -cut model in deterministic and random trees. Berzunza,  Cai, Holmgren. (would have been on arxiv if not for the boat trip).



















✿ A note on the asymptotic

expansion the Lerch's

Transcendent. Cai, J.L. Lopez.

2019. Integral Transforms and

Special functions.

| Graph | LLL | Moments | CLT |
|-------------------------|---|---|---|
| Paths |  |  |  |
| Complete graphs |  |  |  |
| Complete binary trees |  |  |  |
| Conditional GW trees |  |  |  |
| Preferential attachment |  |  | |
| Random recursive trees |  |  | |
| Split trees |  |  | |

The challenge

- Can even 1-cut be studied in *any* random graph?
- *Cannot* use record any more.
- Possible candidate: $G_{n,p}$ with $p = n^{-1} + n^{-4/3}$
- The giant is almost a *GW* tree, plus $O_p(1)$ edges. We choose *root* in the giant *unif. rand.*
- Simulation suggest, on average it takes ($k=1$)

$$1.42 \cdot \sqrt{\text{giant size}}$$

to cut the giant.

- Can we prove this?

should be 1.25 for
GW trees.



Thanks for listening!

